

Ergodic and chaotic behaviour of partial differential equations and applications to biological models

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When can we say that a system is chaotic?

Answer: A system is chaotic if it has a simple and **deterministic** description, but it behaves in a complicated and **"random"** way.

R.R. Math. Meth. Appl. Sci. **27** (2004), 723–738.

R.R. Discrete and Continuous Dynamical Systems **35** (2015), 757–770.

1. **Macroscopic approach:** The existence of global attractors with complicated structure (*strange attractors*).

2. **Microscopic approach:** The existence of trajectories which are unstable, turbulent or dense in the phase space; topological mixing.

3. **Stochastic approach:** The existence of invariant measures having strong ergodic and analytic properties.

X - metric space

$\{S_t\}_{t \geq 0}$ - semiflow on X

a) $S_t : X \rightarrow X$, for $t \geq 0$,

b) $S_0 = \text{Id}$, $S_{t+s} = S_t \circ S_s$, $t, s \geq 0$,

c) $S_t(x)$ is a continuous function of (t, x) .

Example:

$$x'(t) = f(x(t)), \quad x(0) = x_0 \in \mathbb{R}^n$$

$$S_t(x_0) = x(t).$$

Iterates of a transformation $S: X \rightarrow X$ (discrete time semiflow).

Macroscopic approach – strange properties of attractors of a semiflow.

Attractor – a compact set A for which there is an open set U such that:

$$A \subset U,$$

$$S_t(\text{cl } U) \subset U \text{ for } t > 0,$$

$$A = \bigcap_{t>0} S_t(U).$$

An attractor is called a ***strange attractor*** if it is a fractal set, i.e. if it has different topological and Hausdorff dimensions.

Dynamics (on the vertical part of Sh) similar to the **shift transformation on Cantor set**:

$$C = \prod_{n \in \mathbb{N}} \{0, 2\}_n, \quad (Tx)_n = x_{n+1}.$$

$$C = \{a \in [0, 1] : a = \sum_{n=1}^{\infty} a_n 3^{-n}, a_n \in \{0, 2\}\}$$

C is a strange set and trajectories expands:
 $|T^n(x) - T^n(y)| = 3^n|x - y|$ for $n = 1, \dots, n(x, y)$,
 $n(x, y)$ is large if $|x - y|$ is small.

Examples: the logistic map $T(x) = 4x(1 - x)$,
the Smale's horseshoe, the Lorenz' flow and
 $T : H(\mathbb{C}) \rightarrow H(\mathbb{C}), Tf = f'$.

Microscopic approach:

Chaos in the sense of Auslander-Yorke:

- (a) each trajectory is unstable,
- (b) there exists a dense trajectory.

Chaos in the sense of Devaney: (b) + the set of periodic points is dense in X

Topological mixing: for any two open subsets U, V of X there exists $t_0 > 0$ such that

$$S_t(U) \cap V \neq \emptyset \quad \text{for } t \geq t_0.$$

Turbulent trajectory (Lasota-Yorke): no periodic points in the closure of the trajectory.

Turbulent trajectory (Bass):

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T S_t(x) dt = x_0$$

$$\lim_{t \rightarrow \infty} \frac{1}{T} \int_0^T [S_t(x) - x_0][S_{t+\tau}(x) - x_0] dt = \gamma(\tau)$$

$$\gamma(0) \neq 0, \quad \lim_{\tau \rightarrow \infty} \gamma(\tau) = 0.$$

Stochastic approach: probabilistic properties of dynamical systems

μ - probability measure on the σ -algebra $\mathcal{B}(X)$ of Borel subsets of X .

μ **invariant** w.r. $\{S_t\}_{t \geq 0}$ if for $A \in \mathcal{B}(X)$, $t > 0$

$$\mu(S_t^{-1}(A)) = \mu(A).$$

μ is **ergodic** if

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T f(S_t(x)) dt = \int_X f(x) \mu(dx) \quad \mu - \text{a.e.}$$

$f = 1_A \Rightarrow$ (mean time of visiting A) = $\mu(A)$

μ is **mixing** if $\lim_{t \rightarrow \infty} \mu(S_t^{-1}(A) \cap B) = \mu(A)\mu(B)$.

$$\lim_{t \rightarrow \infty} P(S_t(x) \in A \mid x \in B) = \mu(A).$$

μ is **exact** if $\lim_{t \rightarrow \infty} \mu(S_t(A)) = 1$ for $\mu(A) > 0$.

exactness \Rightarrow mixing \Rightarrow ergodicity.

(P) $\text{supp } \mu = X$ (positivity on open sets)

Mixing + (P) \Rightarrow chaos (A-Y)

Ergodicity + (P) \Rightarrow a.a. traj. are dense in X

Mixing + (P) \Rightarrow unstability of all trajectories

Mixing + (P) \Rightarrow topological mixing

Mixing + (P) + exist. of the 2-moment of μ
 \Rightarrow almost all trajectories are turbulent (Bass)

If X is a finite dimensional space, then ergodic properties of transformations and semiflows on X can be successfully investigated by means of Frobenius–Perron operators:

A. Lasota and M.C. Mackey, *Chaos, Fractals and Noise. Stochastic Aspects of Dynamics*, 1994.

(X, Σ, m) a σ -finite measure space, $S : X \rightarrow X$ a measurable transformation s.t.

if $m(A) = 0$, then $m(S^{-1}(A)) = 0$.

The operator $P : L^1(X) \rightarrow L^1(X)$ s.t.

$$\int_A P f(x) m(dx) = \int_{S^{-1}(A)} f(x) m(dx)$$

for all $f \in L^1$ and $A \in \Sigma$ is called *Frobenius–Perron operator* for S .

μ - a probability measure $\mu \ll m$,

Let $f_* = \frac{d\mu}{dm}$ be a density of μ .

μ is invariant under $S \Leftrightarrow Pf_* = f_*$ for $t > 0$.

P F-P operator to the system (X, Σ, μ, S) :

S	P
ergodic	$\mathbf{1}_X$ is a unique invariant density of P
mixing	$w\text{-}\lim_{t \rightarrow \infty} P^t f = \mathbf{1}_X$ for each $f \in D$
exact	$\lim_{t \rightarrow \infty} P^t f = \mathbf{1}_X$ for each $f \in D$

Invariant measure for p.d.e.

A.Lasota, Rend. Sem. Math. Univ. Padova **61**
(1979), 40-48.

$$\frac{\partial u}{\partial t} + x \frac{\partial u}{\partial x} = \lambda u$$

$$S_t v(x) = u(t, x); \quad S_t v(x) = e^{\lambda t} v(e^{-t} x).$$

$$X = \{v \in C[0, 1] : v(0) = 0\}.$$

Theorem 1 *If $\lambda \geq 2$ then there is a continuous ergodic measure μ on X invariant w.r. $\{S_t\}$.*

(continuous $\mu(Per) = 0$)

Lemma 1 *Let $S : X \rightarrow X$ be a continuous map. If for some nonempty compact disjoint sets A and B we have*

$$A \cup B \subset S(A) \cap S(B),$$

then there exists a turbulent trajectory (L-Y).

Lemma 2 *(Bogoluboff-Kriloff). Let $S : X \rightarrow X$ be a continuous map of a compact metric space. Then there exists a probability Borel measure μ invariant and ergodic w.r. S .*

Invariant measure for p.d.e.

R.R. (1985), (1988).

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(g(x)u) = f(x, u)$$

$$u(0, x) = v(x), \text{ for } x \in [0, 1].$$

$$g(0) = 0, \quad g(x) > 0 \text{ for } x \in (0, 1],$$

$$f(0, u_0) = 0, \quad \frac{\partial f}{\partial u}(0, u_*) > 0.$$

$$\{V_t\}_{t \geq 0}, \quad V_t v(x) = u(t, x)$$

$$X = \{v \in C[0, 1] : v(0) = u_*\}.$$

Theorem 2 *There exists a probability measure μ which satisfies:*

(a) *μ is invariant w.r. to $\{V_t\}$,*

(b) *μ is exact,*

(c) *$\text{supp } \mu = X$,*

(d) *$\int_X \|v^2\| \mu(dv) < \infty$.*

Moreover, we proved that the set of periodic points of $\{V_t\}$ is dense in X .

Draft of the proof:

$\{T_t\}$ left-side shift on

$$Y = \{\varphi : [0, \infty) \rightarrow \mathbb{R}\}$$

$$(T_t\varphi)(s) = \varphi(s + t) \text{ for } t, s \geq 0.$$

1. Semiflows (V_t, X) and (T_t, Y) are conjugated (**isomorphic**), a.e. the map $Q : X \rightarrow Y$, given by $Qv_0(t) = v(t, 1)$ is a homeomorphism from X onto $Q(X) \subset Y$ and

$$Q \circ S_t = T_t \circ Q, \quad \text{for } t \geq 0.$$

2. Let $\xi_t = e^t w_{e^{-2t}}$, where $w_t, t \geq 0$ is the Wiener process. Then ξ_t is a stationary Gaussian process with continuous trajectories. Let

$$m(A) = P\{\omega : \xi(\omega) \in A\} \quad A \in \mathcal{B}(Y).$$

The measure m is invariant under $\{T_t\}$ and $m(Q(X)) = 1$. The measure $\nu(A) = m(Q(A))$ is invariant under $\{S_t\}$.

3. **Exactness.** (T_t, Y) is exact iff the σ -algebra $\mathcal{A}_\infty = \bigcap_{t>0} T_t^{-1}(\mathcal{B}(Y))$ contains only sets of measure zero or one.

Let $\mathcal{F}_{\leq t}$ be the σ -algebra generated by $w_s, s \leq t$. Then σ -algebra $T_t^{-1}(\mathcal{B}(Y))$ is generated by $\xi_s, s \geq t$, therefore, $T_t^{-1}(\mathcal{B}(Y)) = \mathcal{F}_{[0, e^{-2t}]}$. Thus $\mathcal{A}_\infty = \bigcap_{r>0} \mathcal{F}_{[0, r]}$ and according to Blumenthal's zero-one law \mathcal{A}_∞ contains only sets of measure zero or one.

4. **Positivity** of ν on open sets can be obtained from the following property of Wiener process:

$$\text{Prob}\{\omega : f(t) < w_t(\omega) < g(t) \text{ for } t \in [a, b]\} > 0.$$

for continuous functions $f < g$ and $0 < a < b$.

Invariant measure for p.d.e.

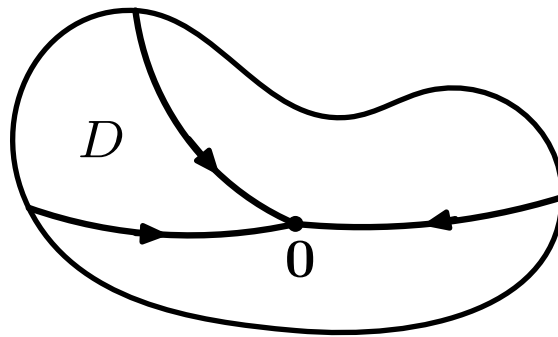
$$\frac{\partial u}{\partial t} + a_1(x) \frac{\partial u}{\partial x_1} + \cdots + a_d(x) \frac{\partial u}{\partial x_d} = f(x, u) \quad (\star)$$

$x \in D$, D diffeomorphic with $B(0, 1)$, $\mathbf{0} \in \text{Int } D$.

$a: D \rightarrow \mathbb{R}^d$ is C^1 function, $a(\mathbf{0}) = \mathbf{0}$.

$$x'(t) = -a(x(t)), \quad x(0) = x_0 \in D, \quad \pi_t x_0 = x(t).$$

Assume that if $x_0 \in D$ then $\pi_t x_0 \in D$ for $t \geq 0$ and $\lim_{t \rightarrow \infty} \pi_t x_0 = \mathbf{0}$.



There exists $u_0^0 \in \mathbb{R}$ such that $f(\mathbf{0}, u_0^0) = 0$ and $\frac{\partial f}{\partial u}(\mathbf{0}, u_0^0) > 0$;

there exist $u_-^0 \in [-\infty, u_0^0)$ and $u_+^0 \in (u_0^0, \infty]$ such that $f(\mathbf{0}, u) < 0$ for $u \in (u_-^0, u_0^0)$ and $f(\mathbf{0}, u) > 0$ for $u \in (u_0^0, u_+^0)$;

if $u_-^0 > -\infty$, then $f(\mathbf{0}, u_-^0) = 0$, $\frac{\partial f}{\partial u}(\mathbf{0}, u_-^0) < 0$;

if $u_+^0 < \infty$, then $f(\mathbf{0}, u_+^0) = 0$, $\frac{\partial f}{\partial u}(\mathbf{0}, u_+^0) < 0$;

Lemma 3 *If $u_-^0 > -\infty$, then there exists a unique stationary solution $u_-: D \rightarrow \mathbb{R}$ of (\star) such that $u_-(\mathbf{0}) = u_-^0$. Analogously if $u_+^0 < \infty$, then ... $u_+(\mathbf{0}) = u_+^0$.*

We set $u_- \equiv -\infty$ if $u_-^0 = -\infty$ and $u_+ \equiv \infty$ if $u_+^0 = \infty$. Let

$$V_0 = \{v \in C(D) : u_-(x) < v(x) < u_+(x) \text{ for } x \in D \text{ and } v(\mathbf{0}) = u_0^0\}.$$

If $v(x) = u(0, x)$, $v \in V_0$, then $S_t v = u(t, \cdot) \in V_0$.

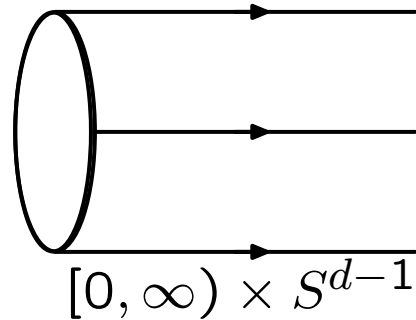
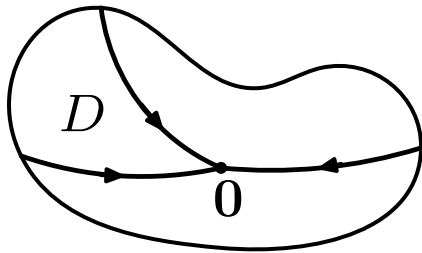
Theorem 3 *There exists a measure m supported on V_0 s.t. $(V_0, \mathcal{B}(V_0), m; S_t)$ is exact.*

Idea of the proof.

1. We replace the Wiener process by *Lévy d -parameter Brownian motion*, which is a Gaussian random field $(\xi(x))$ on \mathbb{R}^d with zero mean and covariance function

$$c(x, y) = E\xi(x)\xi(y) = \frac{1}{2}(|x| + |y| - |x - y|).$$

2. We set $W = C([0, \infty) \times S^{d-1})$ and define a semiflow $(T_t)_{t \geq 0}$ on the space W by $T_t w(s, y) = w(s + t, y)$, $s, t \geq 0$ and $y \in S^{d-1}$.



3. Starting from the random field (ξ_x) we construct an invariant measure μ on the space W invariant w.r. to $(T_t)_{t \geq 0}$ supported on W .
4. We show that systems $(V_0, \mathcal{B}(V_0), m; S_t)$ and $(W, \mathcal{B}(W), \mu; T_t)$ are isomorphic.

If $f(x, u_0^0) \equiv 0$, then we can consider a semiflow (S_t) restricted to the space

$$V_0^+ = \{v \in V_0 : u_0^0 \leq v(x) < u_+(x) \text{ for } x \in D\}.$$

Theorem 4 *There exists a measure m supported on V_0^+ s.t. $(V_0^+, \mathcal{B}(V_0^+), m; S_t)$ is exact.*

Equation in a divergence form

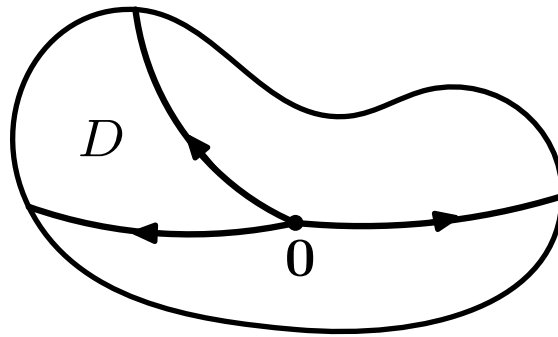
$$\frac{\partial u}{\partial t}(t, x) + \operatorname{div}(a(x)u(t, x)) = g(x, u(t, x)), \quad (**)$$

where $\operatorname{div}(a(x)u(t, x)) = \sum_{i=1}^d \frac{\partial(a_i(x)u(t, x))}{\partial x_i}$.

Eq. (**) describes the growth of a population.

Any individual is characterized by a vector x which changes according to Eq. $x' = a(x)$.

$g(x, u)$ – is a growth rate, $u(t, x)$ is the population distribution w.r. to x .



Eq. (**) can be written in the form (*) with

$$f(x, u) = g(x, u) - u \operatorname{div} a(x).$$

If $g(\mathbf{0}, u_0^0) = u_0^0 \operatorname{div} a(\mathbf{0})$, $\frac{\partial g}{\partial u}(\mathbf{0}, u_0^0) > \operatorname{div} a(\mathbf{0})$

then $f(\mathbf{0}, u_0^0) = 0$, $\frac{\partial f}{\partial u}(\mathbf{0}, u_0^0) > 0$.

Space structure population with logistic growth

We consider a population in which individuals disperse according to equation $x'(t) = a(x)$ and then leave the set D .

Let $g(x, u) = \lambda(1 - u/K(x))u$ be the growth rate. Then the solution of Eq. (**) is the space distribution of the number of individuals in D .

Here $u_0 \equiv 0$. If $\lambda > \operatorname{div} a(\mathbf{0})$ and if

$$u_+^0 = K(\mathbf{0})\left(1 - \lambda^{-1} \operatorname{div} a(\mathbf{0})\right),$$

then there is a stationary solution u_+ of Eq. (**) such that $u_+(\mathbf{0}) = u_+^0$.

According to Theorem 4 there exists a measure m supported on V_0^+ s.t. $(V_0^+, \mathcal{B}(V_0^+), m; S_t)$ is exact, where

$$V_0^+ = \{v \in C(D) : 0 \leq v(x) < u_+(x) \text{ for } x \in D, \\ v(\mathbf{0}) = 0\}.$$

Flow with jumps

We consider a movement of particles with velocity $a(x)$ in the domain D . When a particle reaches the boundary ∂D it jumps to the set D and chooses its new position according to the distribution $v(t, x)$ of other particles.

$$\frac{\partial v}{\partial t}(t, x) + \operatorname{div}(a(x)v(t, x)) = \quad (\clubsuit)$$
$$\left(\int_{\partial D} a(y) \cdot n(y) v(t, y) \sigma(dy) \right) v(t, x).$$

Here $n(y)$ is the outward pointing unit normal to ∂D at y ; $\sigma(dy)$ is the surface measure on ∂D ; and the term between large brackets is the total flow across the boundary ∂D .

If V_0^d the subset of V_0^+ consisting of probability densities, then there exists a measure m supported on V_0^d s.t. the semiflow $(V_0^d, \mathcal{B}(V_0^d), m_d; P_t)$ is exact.

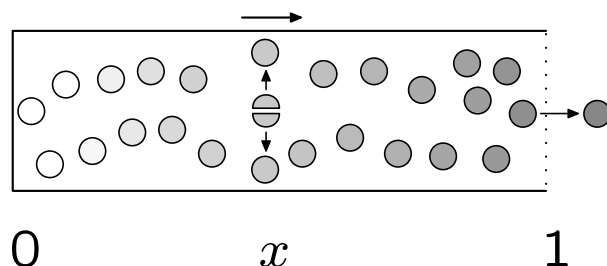
Proof. Let $u(t, x)$ is a positive solution of Eq. (\star) with

$$f(x, u) = (\lambda - \operatorname{div} a(x))u.$$

If $U(t) = \int_D u(t, x) dx$, then $v(t, x) = u(t, x)/U(t)$ is a solution of (\clubsuit) .

Blood cell production system

R.R. Chaos: An Interdisciplinary Journal of Nonlinear Science, **19** (2009), 043112, 1–6.



The evolution of maturity of blood cells in the bone marrow (precursors of any blood cells).

$x' = g(x)$, x -maturity of a cell.

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x}(g(x)u) = g(1)u(t, 1)u(t, x) \quad (1)$$

Corollary 1 *The semiflow $\{U_t\}_{t \geq 0}$ generated by (1) is topologically mixing, chaotic in the sense of Devaney and turbulent in the sense of Bass.*

Size-structured cell population model

R.R. J. Math. Anal. Appl. **393** (2012), 151–165.

x - cell size, $x' = g(x)$

$b(x)$, $d(x)$ - birth i death coefficients,

$$\frac{\partial}{\partial t}u(t, x) + \frac{\partial}{\partial x}(g(x)u(t, x)) = -\mu(x)u(t, x) + 4b(2x)u(t, 2x),$$

where $\mu(x) = d(x) + b(x)$.

Theorem on stability. If $g(2x) \neq 2g(x)$ at least for one x , then there exist $\lambda \in \mathbb{R}$ and a density v^* s.t.

$$\lim_{t \rightarrow \infty} e^{-\lambda t} u(t, x) = C(u(0, x)) v^*(x).$$

Question: What can happen when $g(x) = x$?

$$\frac{\partial u}{\partial t} + x \frac{\partial u}{\partial x} = au(t, x) + bu(t, 2x),$$

El Mourchid, G. Metafune, A. Rhandi and J. Voigt, *J. Math. Anal. Appl.* **339** (2008), 918–924. : $u(t, 2x) \mathbf{1}_{[0, 1/2]}(x)$

Theorem 5 *If $2^{ab} \log 2 < e^{-1}$ and if we choose the space X in a "proper way" then there exists a probability measure μ which satisfies:*

- (a)** μ is invariant w.r. to $\{U_t\}$,
- (b)** μ is mixing,
- (c)** $\text{supp } \mu = X$,
- (d)** $\int_X \|v^2\| \mu(dv) < \infty$.

The set of periodic points of $\{U_t\}$ is dense.

Corollary 2 *The semiflow $\{U_t\}_{t \geq 0}$ is topologically mixing, chaotic in the sense of Devaney and turbulent in the sense of Bass.*

Thank you!